

Parallel and Distributed Computing (B4B36PDV)

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Shared data structures

How to share data between threads?

- Don't.
- Not always possible.
 - databases, graph algorithms,...
- Just put the data behind a mutex, right?
 - Fine if the data structure is not in the hot path.
 - Easily can become a bottleneck.

Reader-writer lock

Mutex that allows multiple readers

- Typically, it is safe to read data from multiple threads.
- But it's not safe to read+write or write+write.
- It's very common to read a lot but write rarely.
- We want to allow multiple readers XOR a single writer.

std::shared_mutex

Coding session 1

RW LOCK

Reader-writer lock

Mutex that allows multiple readers

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- But it's not safe to read+write or write+write.
- It's very common to read a lot but write rarely.
- We want to allow multiple readers XOR a single writer.
- std::shared_mutex
- Higher overhead compared to a mutex.
- Possible writer starvation if there are many readers.

Concurrent data structures

- Break up the data structure into smaller parts.
- Synchronize each part separately.
 - Multiple threads can operate on different parts of the DS without blocking.

CONCURRENT HASH SET

Coding session 2

Concurrent data structures

- Break up the data structure into smaller parts.
- Synchronize each part separately.
 - Multiple threads can operate on different parts of the DS without blocking.
- Sometimes we need to synchronize on the whole DS.
- Typically much faster than locking the whole DS.
- Granularity trade-off
 - The more locks we have, the higher the total overhead.
 - Sometimes we cannot find a good compromise.

Lock-free data structures

Remove all software locking

 Instead of using software mutexes, we can let hardware take care of synchronization -> atomic variables.

- What's a mutex anyway?
- Let us take a small detour...

Atomic variables II

It does not get easier...

- std::atomic<T>
- "Type that only lives in memory."
- What does it give us?
- 1. Ensures that operations on the value are not fragmented.
- 2. Ensures that operations are not implemented using multiple non-atomic operations (e.g., load-modify-store).
- 3. ... is that enough?

ATOMIC VARIABLES

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Coding session 3

Atomic variables II

How about more complex operations?

- Typically, we need to do a more complex operation.
- Often, we can express the operation in three steps:
 - 1. Read the current state from the data structure.
 - 2. Do some thread-local operation (e.g. allocate a node, compare an existing value).
 - 3. Update the data structure with a new value.
- Read-Modify-Write (RMW)
 - You might know the concept from database transactions.

Idea: If we could do the update using a single atomic operation, we'd be much closer to solving the issue.

Compare-and-swap "CAS"

- We have a race condition between the read (step 1) and the update (step 3).
- Instead, we can make the update step conditional.

"If the previously read value is still the same, replace it with this new value."

```
// SINGLE ATOMIC OPERATION
if (*value == previous_value) {
    *value = new_value;
} else {
    previous_value = *value;
}
```

Coding session 4

COMPARE AND SWAP

Lock-free data structures

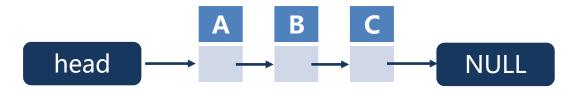
A small disclaimer

Do try this at home.

But (almost) never try it at work!

https://abseil.io/docs/cpp/atomic_danger

- Basic data structure based on a linked list.
- 3 operations:
 - Push
 - Find
 - Pop

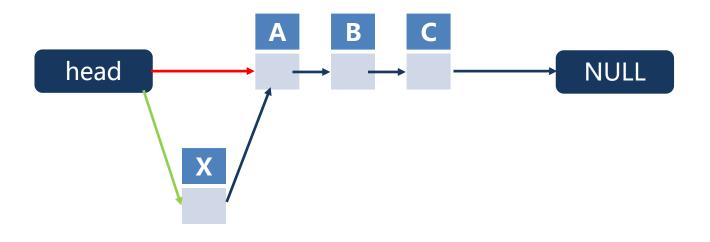


```
class node {
public:
    std::atomic<node*> m_next = nullptr;
    T m_value;
    explicit node(T value)
        : m_value(value) {}
};
```

Push (add new value to the top of the stack)

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```
void push(T value) {
    auto new_node = new node(value);
    auto first_node = m_head.load();
    do {
        new_node->m_next = first_node;
        // if the condition below fails,
        // first_node` is updated to the current value
    } while (!m_head.compare_exchange_weak(first_node, new_node));
```



Find (does the stack contain a specific value?)

Find (does the stack contain a specific value?)

```
bool contains(T value) const {
    auto node = m_head.load();
    while (node != nullptr) {
        if (node->m_value == value) {
            return true;
        }
        node = node->m_next.load();
    }
    return false;
}
```

Pop (remove value from the top of the stack)

Pop (remove value from the top of the stack)

```
// INCORRECT
std::optional<T> pop() {
    auto first_node = m_head.load();
    while (first_node != nullptr) {
        auto second_node = first_node->m_next.load();
        if (m_head.compare_exchange_weak(first_node, second_node))
        Ł
            auto value = first_node->m_value;
            delete first_node;
            return value;
        }
        // retry, first_node is updated to the new value
    }
    return {};
}
```

ABA problem

- If I load an atomic value twice, and the value is still the same, it does not necessarily mean that it did not change in the meantime.
- If someone deallocates a node and then allocates a new one, allocator will often return the just-freed allocation.
- We need to augment the data to unambiguously know if there was a change since the last read.
 - Include a counter next to the pointer.
 - Note that the counter must be a part of the pointer (e.g. HEAD), not the target node.

https://en.wikipedia.org/wiki/ABA_problem#Examples

Node deallocation

- We cannot touch the first node, since it may have been deallocated in the meantime.
- Not a problem in garbage-collected language.
- Very hard to solve in C++ (out of scope for PDV).
 - hazard pointers
 - RCU